

# SEK90-HN050AK02

SEK90

MOTOR FEEDBACK SYSTEMS ROTARY HIPERFACE®

**SICK**  
Sensor Intelligence.

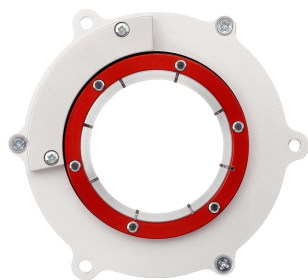


Illustration may differ



### Ordering information

Type	Part no.
SEK90-HN050AK02	1038271

Other models and accessories → [www.sick.com/SEK90](http://www.sick.com/SEK90)

### Detailed technical data

#### Features

<b>Specialty</b>	Stranded cable with strain relief not included in scope of delivery, please order separately (partnumber 2051662), resolver support, plug-in shaft
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#### Performance

<b>Sine/cosine periods per revolution</b>	64
<b>Number of the absolute ascertainable revolutions</b>	1
<b>Total number of steps</b>	2,048 via RS485
<b>Measuring step</b>	5 Winkelsekunden For interpolation of the sine/cosine signals with, e. g., 12 bits
<b>Integral non-linearity</b>	± 72 Winkelsekunden, Error limits for evaluating sine/cosine period, typical values at nominal position ± 0.1 mm und +20 °C
<b>Differential non-linearity</b>	± 45 Winkelsekunden, Non-linearity within a sine/cosine period, typical values at nominal position ± 0.1 mm und +20 °C
<b>Operating speed</b>	≤ 3,000 min <sup>-1</sup> , up to which the absolute position can be reliably produced
<b>Latency period</b>	100 µs
<b>Available memory area</b>	1,792 Byte

#### Interfaces

<b>Type of code for the absolute value</b>	Binary
<b>Code sequence</b>	Increasing, when turning the shaft For clockwise rotation, looking in direction "A" (see dimensional drawing), For clockwise shaft rotation, looking in direction "A" (see dimensional drawing)
<b>Communication interface</b>	HIPERFACE®

#### Electrical data

<b>Connection type</b>	Male connector, M12, 8-pin
<b>Supply voltage</b>	7 V DC ... 12 V DC
<b>Recommended supply voltage</b>	8 V DC
<b>Power consumption</b>	150 mA <sup>1)</sup>

<sup>1)</sup> Without load.

#### Mechanical data

<b>Shaft version</b>	Through hollow shaft
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<b>Shaft diameter</b>	50 mm
<b>Dimensions</b>	See dimensional drawing
<b>Weight</b>	≤ 0.13 kg
<b>Moment of inertia of the rotor</b>	340 gcm <sup>2</sup>
<b>Operating speed</b>	3,000 min <sup>-1</sup>
<b>Angular acceleration</b>	≤ 50,000 rad/s <sup>2</sup>

#### Ambient data

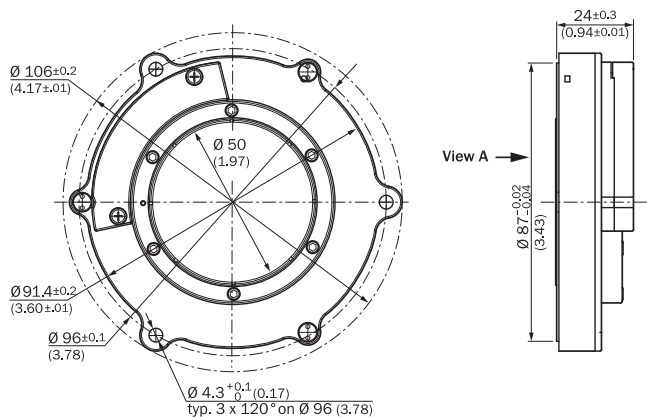
<b>Operating temperature range</b>	-30 °C ... +115 °C
<b>Storage temperature range</b>	-50 °C ... +125 °C, without package
<b>Relative humidity/condensation</b>	90 %, Condensation not permitted
<b>Resistance to shocks</b>	100 g, 6 ms (according to EN 60068-2-27)
<b>Frequency range of resistance to vibrations</b>	30 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)
<b>EMC</b>	According to EN 61000-6-2 and EN 61000-6-3 <sup>1)</sup>
<b>Enclosure rating</b>	IP40, with mating connector inserted and closed cover (according to IEC 60529)

<sup>1)</sup> The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable shield. Users must perform their own tests when other shield designs are used.

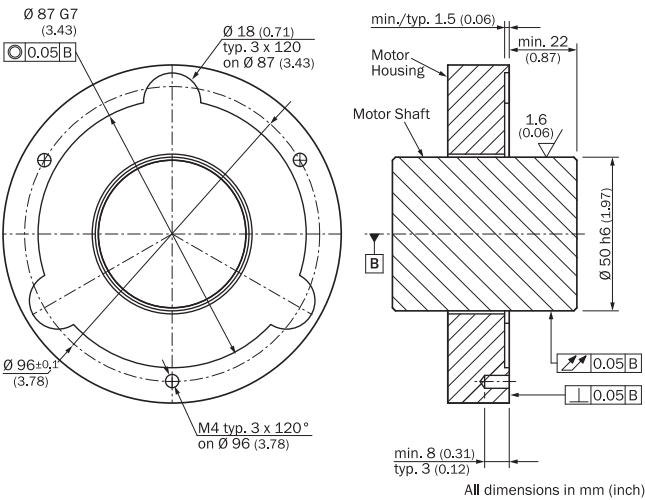
#### Classifications

<b>ECI@ss 5.0</b>	27270590
<b>ECI@ss 5.1.4</b>	27270590
<b>ECI@ss 6.0</b>	27270590
<b>ECI@ss 6.2</b>	27270590
<b>ECI@ss 7.0</b>	27270590
<b>ECI@ss 8.0</b>	27270590
<b>ECI@ss 8.1</b>	27270590
<b>ECI@ss 9.0</b>	27270590
<b>ETIM 5.0</b>	EC001486
<b>ETIM 6.0</b>	EC001486
<b>UNSPSC 16.0901</b>	41112113

#### Dimensional drawing (Dimensions in mm (inch))

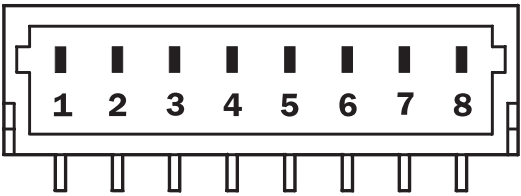


Proposed fitting



PIN assignment

View of the plug-in face

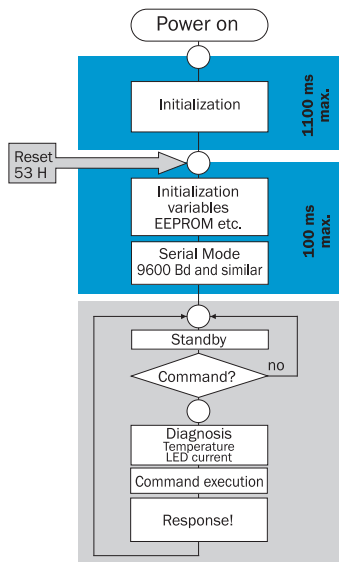
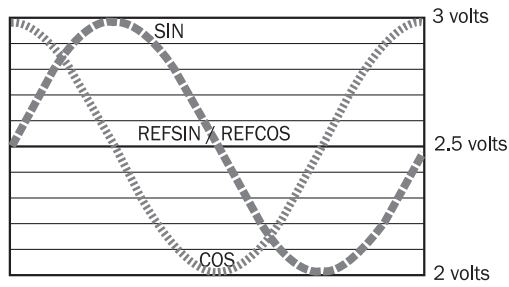


PIN	Signal	Wire colors (cable connection)	Explanation
1	U <sub>S</sub>	Red	Supply voltage
2	+ SIN	White	Process data channel
3	REFSIN	Brown	Process data channel
4	+ COS	Pink	Process data channel
5	REFCOS	Black	Process data channel
6	GND	Blue	Ground connection
7	Data +	Gray or yellow	Parameter channel RS 485
8	Data -	Green or purple	Parameter channel RS 485

The GND connection (0 V) of the supply voltage is not connected to the housing

## Diagrams

Signal diagram for clockwise shaft rotation, looking in direction "A" (see dimensional drawing) 1 period = 360° : 64/128/256





**CAUTION:**  
No **RS485 communication** is possible during the phases highlighted in blue

After a software reset, it will take approx. 150 ms until the SIN/COS signals reach an amplitude of  $1 V_{pp} \pm 20\%$ .

## Recommended accessories

Other models and accessories → [www.sick.com/SEK90](http://www.sick.com/SEK90)

	Brief description	Type	Part no.
Plug connectors and cables			
	Head A: cable Head B: Flying leads Cable: HIPERFACE®, HIPERFACE®, PUR, halogen-free, shielded	LTG-2708-MW	6028361
	Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: HIPERFACE®, unshielded, 0.2 m	DOL-0J08-G0M2XB6	2031086
	Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: HIPERFACE®, shielded, 0.5 m	DOL-0J08-G0M5XB6	2056250

## SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is “Sensor Intelligence.”

## WORLDWIDE PRESENCE:

Contacts and other locations –[www.sick.com](http://www.sick.com)