

INCREMENTAL ENCODERS



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Ordering information

Туре	Part no.
DFS60A-TEPL65536	1036972

Other models and accessories -> www.sick.com/DFS60

Illustration may differ



Detailed technical data

Performance

Pulses per revolution	65,536 ¹⁾		
Measuring step	90° electronically/ppr		
Measuring step deviation at binary number of lines	± 0.0015°		
Error limits	± 0.03°		
Initialization time	32 ms ²⁾ 30 ms		

 $^{(1)}$ See maximum revolution range.

 $^{\rm 2)}\,\rm With$ mechanical zero pulse width.

Interfaces

Communication interface	Incremental
Communication Interface detail	TTL / HTL
Factory setting	Factory setting: output level TTL
Number of signal channels	6-channel
Programmable/configurable	1

Electrical data

Connection type	Cable, 8-wire, universal, 3 m
Operating current	40 mA
Power consumption	≤ 0.7 W (without load)
Supply voltage	4.5 V 32 V
Load current	≤ 30 mA
Output frequency	≤ 820 kHz
Reference signal, number	1

¹⁾ Programming TTL with \geq 5.5 V: short-circuit opposite to another channel or GND permissable for maximum 30 s.

²⁾ Programming HTL or TTL with < 5.5 V: short-circuit opposite to another channel, US or GND permissable for maximum 30 s.

³⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

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Reference signal, position	90°, electric, logically gated with A and B		
Reverse polarity protection	✓		
Short-circuit protection of the outputs	✓ ^{1) 2)}		
MTTFd: mean time to dangerous failure	300 years (EN ISO 13849-1) ³⁾		

¹⁾ Programming TTL with \geq 5.5 V: short-circuit opposite to another channel or GND permissable for maximum 30 s.

 $^{2)}$ Programming HTL or TTL with < 5.5 V: short-circuit opposite to another channel, US or GND permissable for maximum 30 s.

³⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Mechanical data

Mechanical design	Through hollow shaft
Shaft diameter	12 mm
Weight	0.2 kg
Shaft material	Metal
Flange material	Aluminum
Housing material	Aluminum die cast
Start up torque	0.8 Ncm (+20 °C)
Operating torque	0.6 Ncm (+20 °C)
Permissible shaft movement, axial stat- ic/dynamic	± 0.5 mm / ± 0.01 mm
Permissible shaft movement, radial stat- ic/dynamic	± 0.3 mm / ± 0.05 mm
Operating speed	≤ 9,000 min ^{-1 1)}
Moment of inertia of the rotor	40 gcm ²
Bearing lifetime	3.6 x 10^10 revolutions
Angular acceleration	≤ 500,000 rad/s²

 $^{1)}$ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3		
Enclosure rating	IP65, housing side, cable connection (according to IEC 60529) IP65, shaft side (according to IEC 60529)		
Permissible relative humidity	90 $\%$ (condensation of the optical scanning not permitted)		
Operating temperature range	-40 °C +100 °C ¹⁾ -30 °C +100 °C ²⁾		
Storage temperature range	-40 °C +100 °C, without package		
Resistance to shocks	100 g, 6 ms (according to EN 60068-2-27)		
Resistance to vibration	30 g, 10 Hz 2,000 Hz (according to EN 60068-2-6)		

 $^{\mbox{1})}$ Stationary position of the cable.

 $^{2)}$ Flexible position of the cable.

Classifications

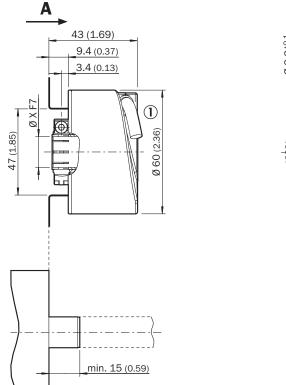
ECI@ss 5.0	27270501
ECI@ss 5.1.4	27270501
ECI@ss 6.0	27270590

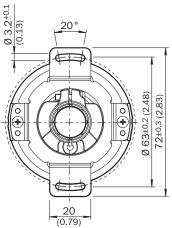
INCREMENTAL ENCODERS

ECI@ss 6.2	27270590
ECI@ss 7.0	27270501
ECI@ss 8.0	27270501
ECI@ss 8.1	27270501
ECI@ss 9.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

Through hollow shaft, cable connection





General tolerances according to DIN ISO 2768-mk (1) Cable diameter = 5.6 mm +/- 0.2 mm bend radius = 30 mm

Type Through hollow shaft	Shaft diameter XF7	Shaft diameter xj7
DFS60x-TAxxxxxxx	6 mm	Provided by customer
DFS60x-TBxxxxxxxx	8 mm	
DFS60x-TCxxxxxxx	3/8"	
DFS60x-TDxxxxxxxx	10 mm	
DFS60x-TExxxxxxx	12 mm	
DFS60x-TFxxxxxxx	1/2″	
DFS60x-TGxxxxxxx	14 mm	

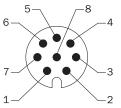
INCREMENTAL ENCODERS

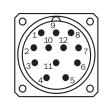
Type Through hollow shaft	Shaft diameter XF7	Shaft diameter xj7
DFS60x-THxxxxxxxx	15 mm	
DFS60x-TJxxxxxxxx	5/8″	

PIN assignment

Cable, 8-wire

View of M12 male device connector on encoder





View of M23 male device connector on encoder

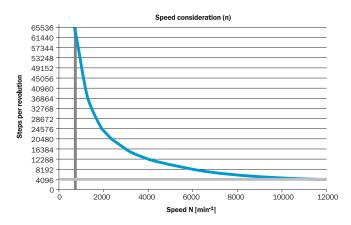
PIN, 8-pin, M12 male connector	PIN, 12-pin, M23 male connector	Color of the wires for encoders with cable outlet	TTL/HTL signal	Sin/cos 1.0 V _{ss}	Explanation
1	6	Brown	A	COS-	Signal wire
2	5	White	A	COS+	Signal wire
3	1	Black	В	SIN-	Signal wire
4	8	Pink	В	SIN+	Signal wire
5	4	Yellow	⁻ z	⁻ z	Signal wire
6	3	Violet	Z	Z	Signal wire
7	10	Blue	GND	GND	Ground connection of the encoder
8	12	Red	+U _s	+U _s	Supply voltage (volt-free to housing)
-	9	-	n.c.	n.c.	Not assigned
-	2	-	n.c.	n.c.	Not assigned
-	11	-	n.c.	n.c.	Not assigned
-	7 1)	-	0-SET 1)	n.c.	Set zero pulse 1)
Screen	Screen	Screen	Screen	Screen	Screen connected to housing on encod- er side. Connected to ground on control side.

¹⁾ For electrical interfaces only: M, U, V, W with 0-SET function on PIN 7 on M23 male connector. The 0-SET input is used to set the zero pulse on the current shaft position. If the 0-SET input is connected to U_s for longer than 250 ms after it had previously been unassigned for at least 1,000 ms or had been connected to the GND, the current position of the shaft is assigned to the zero pulse signal "Z".

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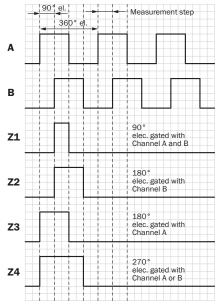
Maximum revolution range

Maximum revolution range



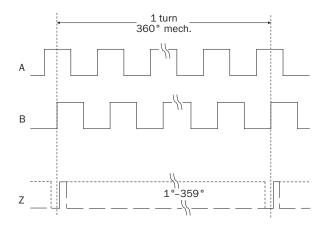
Diagrams

Electrical zero pulse width can be configured to 90°, 180°, or 270°. Width of the zero pulse in relation to a pulse period.



Cw with view on the encoder shaft in direction "A", compare dimensional drawing.

Mechanical zero pulse width 1° to 359° programmable. Width of the zero pulse in relation to a mechanical revolution of the shaft.



Recommended accessories

Other models and accessories -> www.sick.com/DFS60

	Brief description	Туре	Part no.		
Flanges					
Ŵ	Standard stator coupling	BEF-DS00XFX	2056812		
Other mounting accessories					
	Bearing bracket for hollow shaft encoders, fastening screws included the Bearing Block is intended for very large radial and axial shaft loads. Particularly for application on: Belt pulleys, Chain pinions, Friction wheels. It is designed this way to enable fitting of encoder with blind hollow shaft with \emptyset 12 mm., fastening screws included	BEF-FA-B12-010	2042728		
	Clamping ring for metal hollow shaft, metal	BEF-KR-M	2064709		
Plug connectors and cables					
J.	Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 5 m	DOL-0J08-G05MAA3	2046876		
	Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 0.5 m	DOL-0J08-G0M5AA3	2046873		
	Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 10 m	DOL-0J08-G10MAA3	2046877		
	Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: SSI, Incremental, PUR, halogen-free, shielded, 1.5 m	DOL-0J08-G1M5AA6	2048590		
	Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: SSI, Incremental, PUR, halogen-free, shielded, 3 m	DOL-0J08-G3M0AA6	2048591		

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	Brief description	Туре	Part no.	
	Head A: female connector, terminal box, 8-pin, straight Head B: male connector, D-Sub, 9-pin, straight Cable: Incremental, PVC, shielded, 0.5 m	DSL-0D08-G0M5AC3	2061739	
	Head A: female connector, JST, 8-pin, straight Head B: male connector, M23, 12-pin, straight Cable: Incremental, PUR, halogen-free, shielded, 1 m	STL-2312-G01MAA3	2061622	
	Head A: female connector, JST, 8-pin, straight Head B: male connector, M23, 12-pin, straight Cable: Incremental, PUR, halogen-free, shielded, 2 m	STL-2312-G02MAA3	2061504	
	Head A: female connector, JST, 8-pin, straight Head B: male connector, M23, 12-pin, straight Cable: Incremental, PUR, halogen-free, shielded, 0.35 m	STL-2312-GM35AA3	2061621	
	Head A: male connector, M12, 8-pin, straight, A-coded Head B: - Cable: Incremental, shielded	STE-1208-GA01	6044892	
	Head A: male connector, M23, 12-pin, straight Head B: - Cable: HIPERFACE [®] , SSI, Incremental, shielded	STE-2312-G01	2077273	
		STE-2312-GX	6028548	
Programming and configuration tools				
	USB programming unit, for programmable SICK encoders AFS60, AFM60, DFS60, VFS60, DFV60 and wire draw encoders with programmable encoders	PGT-08-S	1036616	
	Programming unit display for programmable SICK DFS60, DFV60, AFS/AFM60, AHS/ AHM36 encoders, and wire draw encoder with DFS60, AFS/AFM60 and AHS/AHM36. Compact dimensions, low weight, and intuitive operation.	PGT-10-Pro	1072254	

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SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

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For us, that is "Sensor Intelligence."

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