

INCREMENTAL ENCODERS



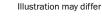
INCREMENTAL ENCODERS



Ordering information

| Туре | Part no. |
|------------------|----------|
| DFS60B-BHPM10000 | 1036803 |

Other models and accessories -> www.sick.com/DFS60





Detailed technical data

Performance

| Pulses per revolution | 10,000 ¹⁾ |
|--|------------------------------|
| Measuring step | 90° electronically/ppr |
| Measuring step deviation at non binary number of lines | ± 0.01° |
| Error limits | ± 0.05° |
| Initialization time | 32 ms ²⁾ 30 ms |

¹⁾ See maximum revolution range.

²⁾ With mechanical zero pulse width.

Interfaces

| Communication interface | Incremental |
|--------------------------------|-----------------------------------|
| Communication Interface detail | TTL / HTL |
| Factory setting | Factory setting: output level TTL |
| Number of signal channels | 6-channel |
| Programmable/configurable | 1 |

Electrical data

| Connection type | Cable, 8-wire, universal, 5 m |
|----------------------------|---|
| Operating current | 40 mA |
| Power consumption | \leq 0.7 W (without load) |
| Supply voltage | 4.5 V 32 V |
| Load current | ≤ 30 mA |
| Output frequency | ≤ 600 kHz |
| Reference signal, number | 1 |
| Reference signal, position | 90°, electric, logically gated with A and B |

¹⁾ Programming TTL with \geq 5.5 V: short-circuit opposite to another channel or GND permissable for maximum 30 s.

²⁾ Programming HTL or TTL with < 5.5 V: short-circuit opposite to another channel, US or GND permissable for maximum 30 s.

³⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

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| Reverse polarity protection | ✓ |
|---|--|
| Short-circuit protection of the outputs | ✓ ^{1) 2)} |
| MTTFd: mean time to dangerous failure | 300 years (EN ISO 13849-1) ³⁾ |

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| Mecha | anical | data |
|-------|--------|------|
| | anncar | uala |

| Mechanical design | Blind hollow shaft |
|--|------------------------------------|
| Shaft diameter | 15 mm |
| Weight | 0.2 kg |
| Shaft material | Metal |
| Flange material | Aluminum |
| Housing material | Aluminum die cast |
| Start up torque | 0.8 Ncm (+20 °C) |
| Operating torque | 0.6 Ncm (+20 °C) |
| Permissible shaft movement, axial stat- ic/dynamic | ± 0.5 mm / ± 0.2 mm |
| Permissible shaft movement, radial stat- ic/dynamic | ± 0.3 mm / ± 0.1 mm |
| Operating speed | ≤ 6,000 min ^{-1 1)} |
| Moment of inertia of the rotor | 40 gcm ² |
| Bearing lifetime | 3.6 x 10 ¹⁰ revolutions |
| Angular acceleration | ≤ 500,000 rad/s² |

 $^{1)}$ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

| EMC | According to EN 61000-6-2 and EN 61000-6-3 |
|-------------------------------|--|
| Enclosure rating | IP67, housing side, cable connection (according to IEC 60529) IP65, shaft side (according to IEC 60529) |
| Permissible relative humidity | 90 % (condensation of the optical scanning not permitted) |
| Operating temperature range | -40 °C +100 °C ¹⁾ -30 °C +100 °C ²⁾ |
| Storage temperature range | -40 °C +100 °C, without package |
| Resistance to shocks | 70 g, 6 ms (according to EN 60068-2-27) |
| Resistance to vibration | 30 g, 10 Hz 2,000 Hz (according to EN 60068-2-6) |

 $^{1)}\ensuremath{\,\text{Stationary position of the cable.}}$

 $^{2)}$ Flexible position of the cable.

Classifications

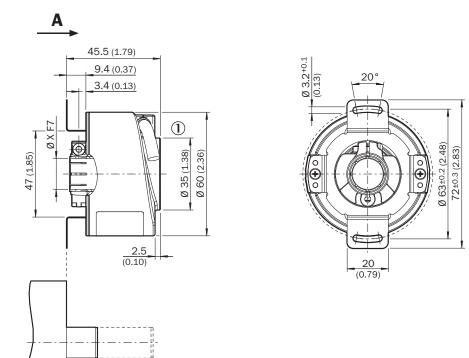
| ECI@ss 5.0 | 27270501 |
|--------------|----------|
| ECI@ss 5.1.4 | 27270501 |
| ECI@ss 6.0 | 27270590 |
| ECI@ss 6.2 | 27270590 |

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| ECI@ss 7.0 | 27270501 |
|----------------|----------|
| ECI@ss 8.0 | 27270501 |
| ECI@ss 8.1 | 27270501 |
| ECI@ss 9.0 | 27270501 |
| ETIM 5.0 | EC001486 |
| ETIM 6.0 | EC001486 |
| UNSPSC 16.0901 | 41112113 |

Dimensional drawing (Dimensions in mm (inch))

Blind hollow shaft, cable outlet



General tolerances according to DIN ISO 2768-mk ① Cable diameter = 5.6 mm +/- 0.2 mm bend radius = 30 mm

min. 15 (0.59)

max. 42 (1.65)

| Type Blind hollow shaft | Shaft diameter XF7 | Shaft diameter xj7 |
|----------------------------|--------------------|----------------------|
| DFS60x-BAxxxxxxxx | 6 mm | Provided by customer |
| DFS60x-BBxxxxxxxx | 8 mm | |
| DFS60x-BCxxxxxxxx | 3/8" | |
| DFS60x-BDxxxxxxxx | 10 mm | |
| DFS60x-BExxxxxxxx | 12 mm | |
| DFS60x-BFxxxxxxxx | 1/2″ | |
| DFS60x-BGxxxxxxxx | 14 mm | |
| DFS60x-BHxxxxxxxx | 15 mm | |

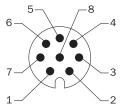
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| Type Blind hollow shaft | Shaft diameter XF7 | Shaft diameter xj7 |
|----------------------------|--------------------|--------------------|
| DFS60x-BJxxxxxxxx | 5/8″ | |

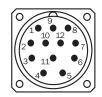
PIN assignment

Cable, 8-wire

View of M12 male device connector on encoder



View of M23 male device connector on encoder



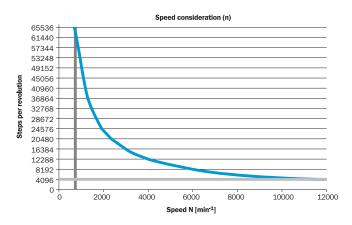
| PIN, 8-pin, M12 male connector | PIN, 12-pin, M23 male connector | Color of the wires for encoders with cable outlet | TTL/HTL signal | $\mathrm{Sin/cos}~\mathrm{1.0~V}_{\mathrm{SS}}$ | Explanation |
|-----------------------------------|---------------------------------|---|-----------------|---|---|
| 1 | 6 | Brown | A | COS- | Signal wire |
| 2 | 5 | White | A | COS+ | Signal wire |
| 3 | 1 | Black | -в | SIN- | Signal wire |
| 4 | 8 | Pink | В | SIN+ | Signal wire |
| 5 | 4 | Yellow | Z | ⁻ z | Signal wire |
| 6 | 3 | Violet | Z | Z | Signal wire |
| 7 | 10 | Blue | GND | GND | Ground connection of the encoder |
| 8 | 12 | Red | +U _s | +U _s | Supply voltage (volt-free to housing) |
| - | 9 | - | n.c. | n.c. | Not assigned |
| - | 2 | - | n.c. | n.c. | Not assigned |
| - | 11 | - | n.c. | n.c. | Not assigned |
| - | 7 1) | - | 0-SET 1) | n.c. | Set zero pulse 1) |
| Screen | Screen | Screen | Screen | Screen | Screen connected to housing on encod- er side. Connected to ground on control side. |

¹⁾ For electrical interfaces only: M, U, V, W with 0-SET function on PIN 7 on M23 male connector. The 0-SET input is used to set the zero pulse on the current shaft position. If the 0-SET input is connected to U_s for longer than 250 ms after it had previously been unassigned for at least 1,000 ms or had been connected to the GND, the current position of the shaft is assigned to the zero pulse signal "Z".

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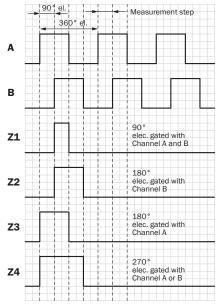
Maximum revolution range

Maximum revolution range



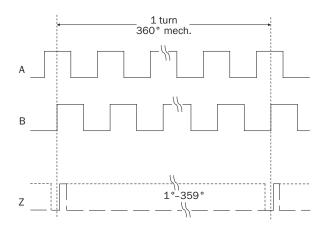
Diagrams

Electrical zero pulse width can be configured to 90°, 180°, or 270°. Width of the zero pulse in relation to a pulse period.



Cw with view on the encoder shaft in direction "A", compare dimensional drawing.

Mechanical zero pulse width 1° to 359° programmable. Width of the zero pulse in relation to a mechanical revolution of the shaft.



Recommended accessories

Other models and accessories -> www.sick.com/DFS60

| | Brief description | Туре | Part no. | | | |
|----------------------------|---|------------------|----------|--|--|--|
| Flanges | | | | | | |
| Ŵ | Standard stator coupling | BEF-DS00XFX | 2056812 | | | |
| Other mounting accessories | | | | | | |
| | Clamping ring for metal hollow shaft, metal | BEF-KR-M | 2064709 | | | |
| Plug connecto | rs and cables | | | | | |
| A. | Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 5 m | DOL-0J08-G05MAA3 | 2046876 | | | |
| | Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 0.5 m | DOL-0J08-G0M5AA3 | 2046873 | | | |
| | Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 10 m | DOL-0J08-G10MAA3 | 2046877 | | | |
| | Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: SSI, Incremental, PUR, halogen-free, shielded, 1.5 m | DOL-0J08-G1M5AA6 | 2048590 | | | |
| | Head A: female connector, JST, 8-pin, straight Head B: Flying leads Cable: SSI, Incremental, PUR, halogen-free, shielded, 3 m | DOL-0J08-G3M0AA6 | 2048591 | | | |
| | Head A: female connector, terminal box, 8-pin, straight Head B: male connector, D-Sub, 9-pin, straight Cable: Incremental, PVC, shielded, 0.5 m | DSL-0D08-G0M5AC3 | 2061739 | | | |
| | Head A: female connector, JST, 8-pin, straight Head B: male connector, M23, 12-pin, straight Cable: Incremental, PUR, halogen-free, shielded, 1 m | STL-2312-G01MAA3 | 2061622 | | | |

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| | Brief description | Туре | Part no. | | | |
|-------------------------------------|--|------------------|----------|--|--|--|
| | Head A: female connector, JST, 8-pin, straight Head B: male connector, M23, 12-pin, straight Cable: Incremental, PUR, halogen-free, shielded, 2 m | STL-2312-G02MAA3 | 2061504 | | | |
| | Head A: female connector, JST, 8-pin, straight Head B: male connector, M23, 12-pin, straight Cable: Incremental, PUR, halogen-free, shielded, 0.35 m | STL-2312-GM35AA3 | 2061621 | | | |
| | Head A: male connector, M12, 8-pin, straight, A-coded Head B: - Cable: Incremental, shielded | STE-1208-GA01 | 6044892 | | | |
| TO | Head A: male connector, M23, 12-pin, straight Head B: - Cable: HIPERFACE [®] , SSI, Incremental, shielded | STE-2312-G01 | 2077273 | | | |
| | | STE-2312-GX | 6028548 | | | |
| Programming and configuration tools | | | | | | |
| | USB programming unit, for programmable SICK encoders AFS60, AFM60, DFS60, VFS60, DFV60 and wire draw encoders with programmable encoders | PGT-08-S | 1036616 | | | |
| | Programming unit display for programmable SICK DFS60, DFV60, AFS/AFM60, AHS/ AHM36 encoders, and wire draw encoder with DFS60, AFS/AFM60 and AHS/AHM36. Compact dimensions, low weight, and intuitive operation. | PGT-10-Pro | 1072254 | | | |

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